

# Faculty of Engineering & Technology

# **Control Systems 2**

#### **Information:**

Course Code: CMP 472 Level: Undergraduate Course Hours: 3.00- Hours

**Department:** Specialization of Electrical Power Engineering

Instructor Information :					
Title	Name	Office hours			
Professor	Hany Mohamed Hasanien Mohamed	2			
Lecturer	Sameh Abdelhaleem Mohamed Abdelsalam	2			
Assistant Lecturer	Mohamed Abdallah Mahmoud Shaheen	6			
Teaching Assistant	TOAA ABDELSALAM ELSAYED MOHAMED				
Teaching Assistant	Ahmed Mahmoud Mohamed Mahmoud Hegazy				

### Area Of Study:

#### **Description:**

Discrete-time signals and systems; z-Transform analysis; Pulse transfer function and discrete-time feedback system; Static error, Jury stability test, and system sensitivity; Frequency-domain and state space analysis and design of discrete-time systems using Matlab; Digital controller implementation issues.

<u>Course οι</u>	tcomes:			
a.Knowled	lge and Understanding: :			
1 -	Outline the Mathematical Modeling of different digital control systems.			
2 -	Illustrate the stability of control systems, transient response and steady-state error.			
3 -	Explain the root locus and bode diagram for control systems and the design of digital controllers using conventional methods			
4 -	Illustrate the state space representation, analysis and the steps of the design of controllers and observers.			
.Intellect	ual Skills: :			
1 -	Select appropriate mathematical and computer-based methods for modeling and analyzing problems			
2 -	Design digital control systems applying appropriate knowledge and principles			
3 -	Select appropriate solutions for engineering problems based on analytical thinking.			
4 -	Analyze system, processes and components critically.			

Ænrich Studentsoknowledge with the basic concepts of discrete-time control systems (Digital Control Systems) Discrete Linear Time Invariant systems only will be considered.

<sup>\*\*</sup>Comprehend Transient response analysis and

<sup>&</sup>quot;ÁDevelop studentsækills for Steady state error analysis, Stability analysis, Root locus analysis and Frequency response method, and State space methods.



# c.Professional and Practical Skills::

- 1 Write MatLab code for developed design methods.
- 2 Apply gained hardware and software skills to controller design in diverse applications

# d.General and Transferable Skills::

- 1 Collaborate effectively within multidisciplinary team.
- 2 Communicate effectively

Course Topic And Contents :					
Topic	No. of hours	Lecture	Tutorial / Practical		
The z Transform	5	3	2		
The Pulse Transfer Function	5	3	2		
Mapping between the s Plane and the z Plane	5	3	2		
Transient and Steady-State Response Analysis	5	3	2		
The Root Locus Methods	5	3	2		
Design Based on The Root Locus Methods	10	6	4		
Bode Diagrams	5	3	2		
Design Based on Bode Diagrams	10	6	4		
State Space Representation and Analysis	5	3	2		
Pole Placement Design	5	3	2		
State Observers	5	3	2		
Servo Systems	5	3	2		

# **Teaching And Learning Methodologies:**

Interactive Lecture

Problem based learning

Discussion

**Experiential learning** 

Course Assessment :						
Methods of assessment	Relative weight %	Week No	Assess What			
Assignment	7.00					
Computer Assignment	8.00					
Final exam	40.00					
Mid- Exam 1I	15.00					
Mid- Exam I	15.00					
Participation	5.00					
Quizzes	10.00					



# **Recommended books:**

ÁDigital Control System Analysis and Design, Charles L. Phillips, H. Troy Nagle, 3rd Edition, 1994, Prentice-Hall ÁDigital Control of Dynamic Systems, G. Franklin and J. Powell and M. Workman, 3rd Edition, 1998, Prentice-Hall ÁDiscrete Time Control Problems Using Matlab by Joe H. Chow, Dean K. Frederick, Nicolas W. Chbat, October 2002, CL Engineering

"ÁPeriodicals, Web Sites, õ Ástc Any web site on control systems